

# Understanding collective phenomena in multicellular systems through agent-based models



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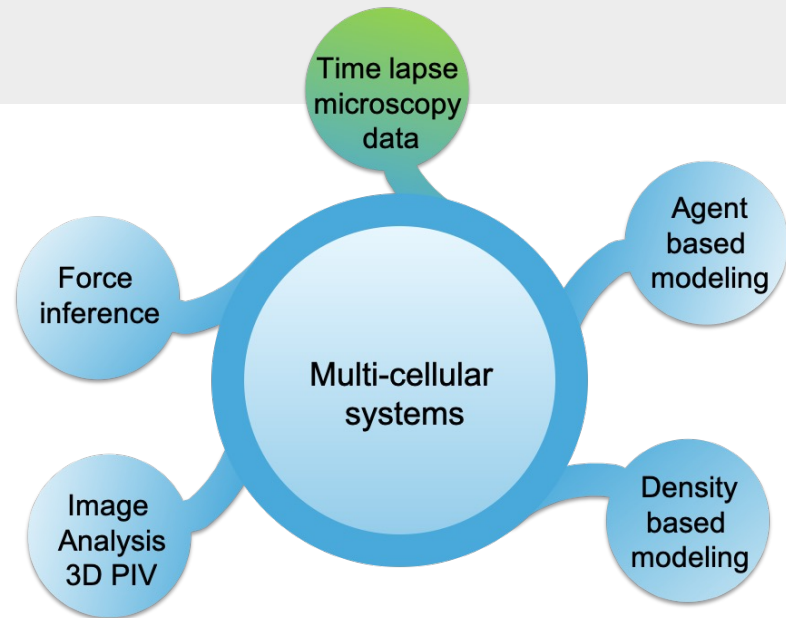
Franziska Matthäus, FIAS & Goethe University Frankfurt,  
Department of Computer Science and Mathematics, Frankfurt, Germany

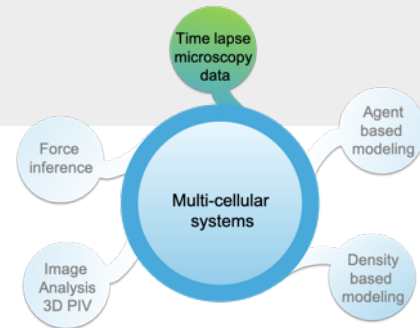
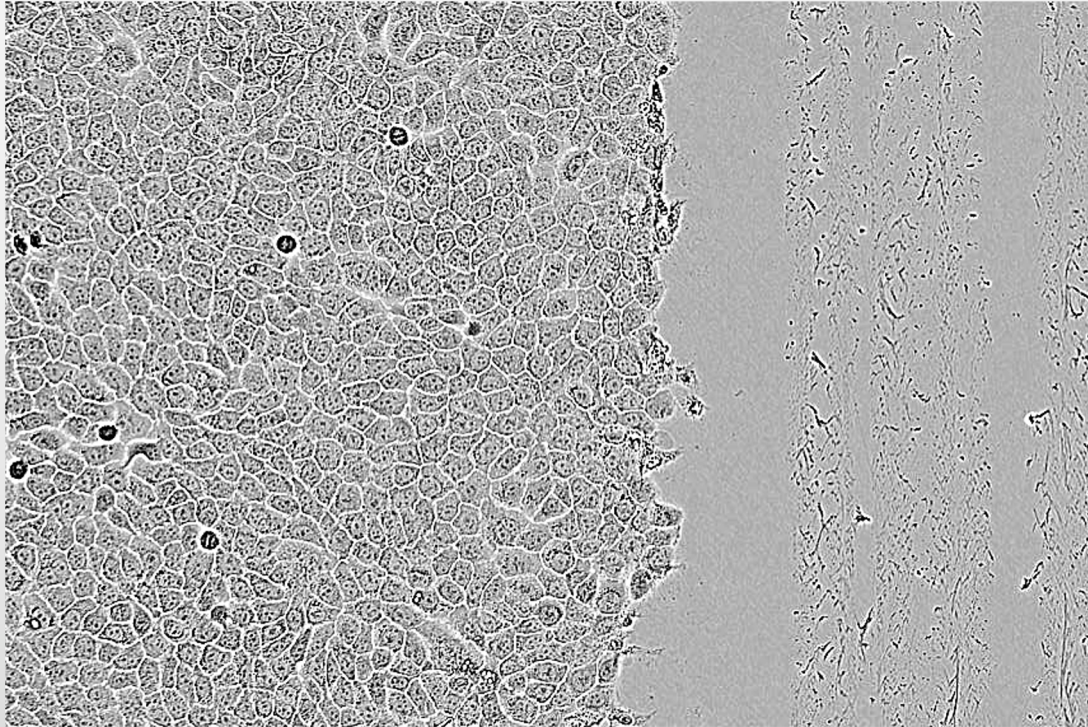
**Multi-cellular systems** exhibit a range of behaviors that can be studied using agent-based approaches;

- Collective phenomena
- Self-organization & pattern formation
- Structure – function relationship
- mechano-chemical regulation
- Active vs. passive mechanisms in biological systems

### Goal:

The identification of *simple principles* of complex behavior:  
How does *local information* generate *global structure*?





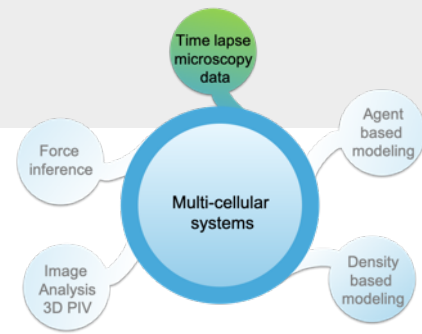
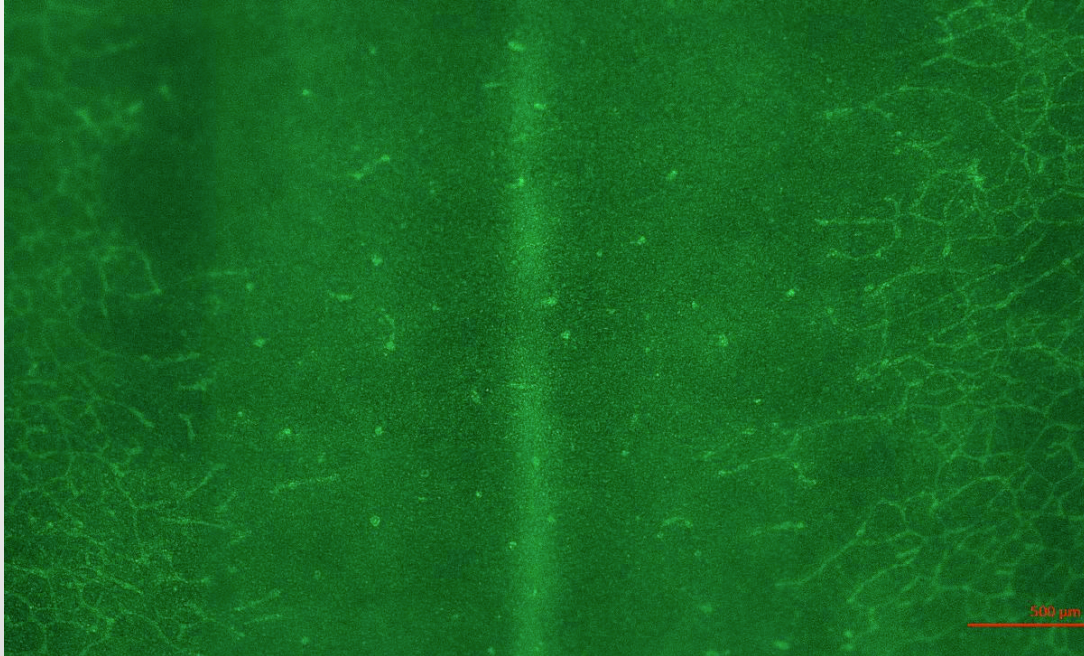
2D / 3D time-lapse microscopy data

Wound healing  
(with AK Windbergs, FB 14)

Skin patterning  
(With D. Headon, Roslin Institute, UK)

Organoid dynamics  
(with AK Stelzer, FB 15)

Development  
(with AK Stelzer, FB 15, J. Rainger  
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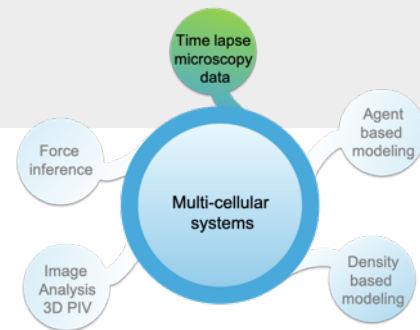
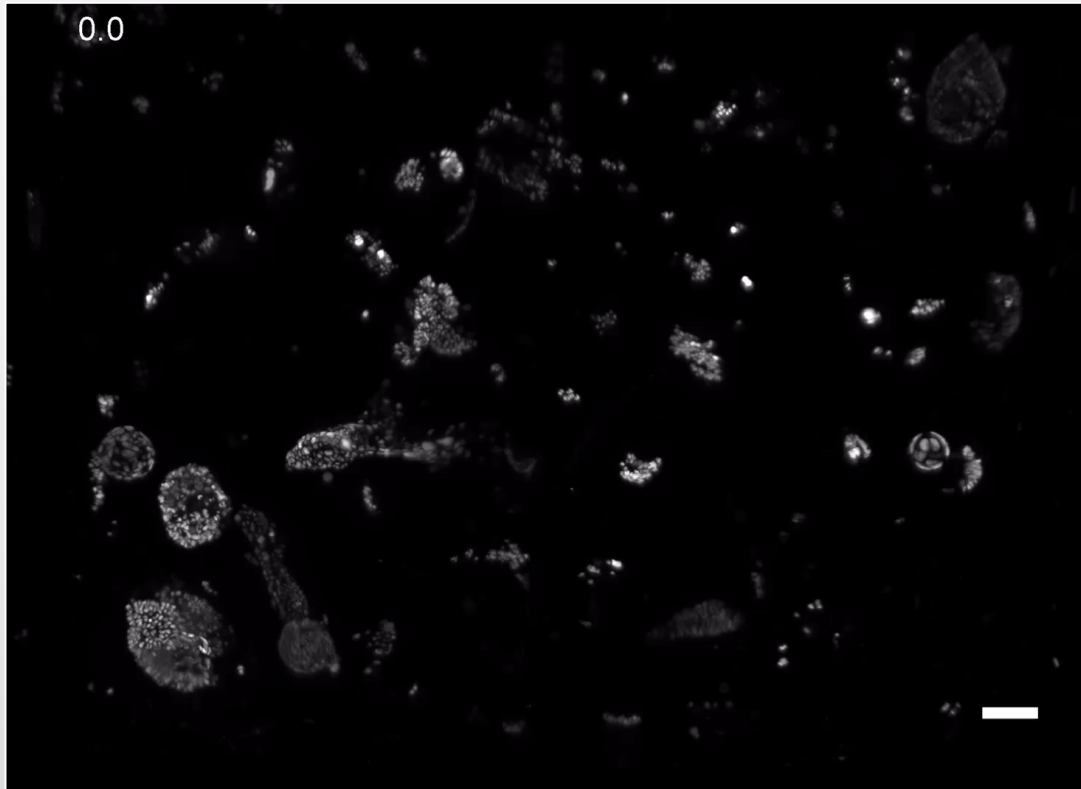
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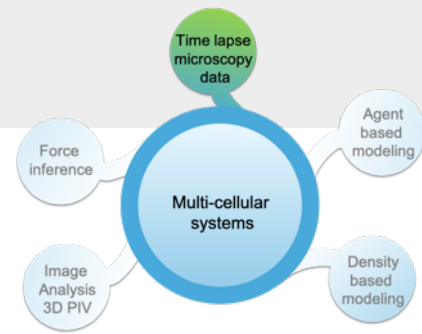
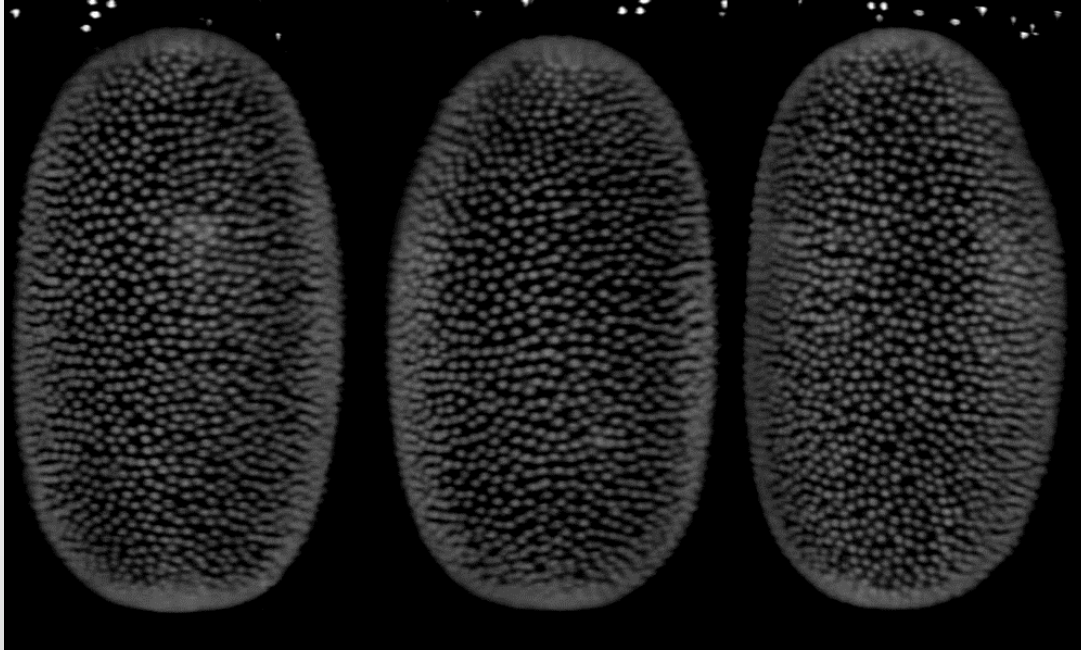
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## Agent-based modeling toolkit

# Agent-based Modeling Toolkit



Centroid position    adhesion/repulsion

$$\frac{\partial \mathbf{x}_i}{\partial t} = \sum_{j \in \mathcal{N}} \mathbf{F}_{i,j} + \mathbf{v} + \xi(t)$$

random motion

Active migration

$$\frac{\partial \mathbf{v}}{\partial t} = \frac{1}{\tau} \left( \sum_{j \in \mathcal{N}} \mathbf{F}_{i,j} - \mathbf{v} \right)$$

mechanotransduction, persistence, friction

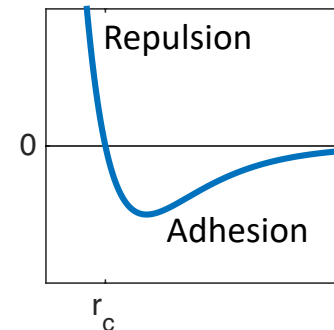
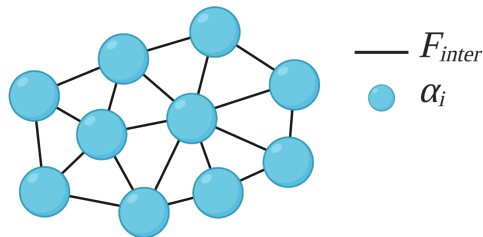
Forces

$$\mathbf{F} = F_0 \cdot F(\|\mathbf{x}_i - \mathbf{x}_j\|) \frac{\mathbf{x}_i - \mathbf{x}_j}{\|\mathbf{x}_i - \mathbf{x}_j\|}$$

Force potential

$$F(r) = \begin{cases} 2 \cdot e^{-2a(r-r_c)} - e^{-a(r-r_c)}, & r < \sigma r_c \\ 0, & r \geq \sigma r_c \end{cases}$$

Cell neighborhood via Gabriel net  
(distance based) or Delaunay triangulation



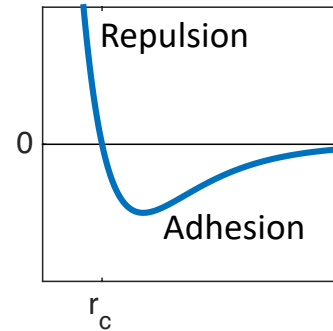


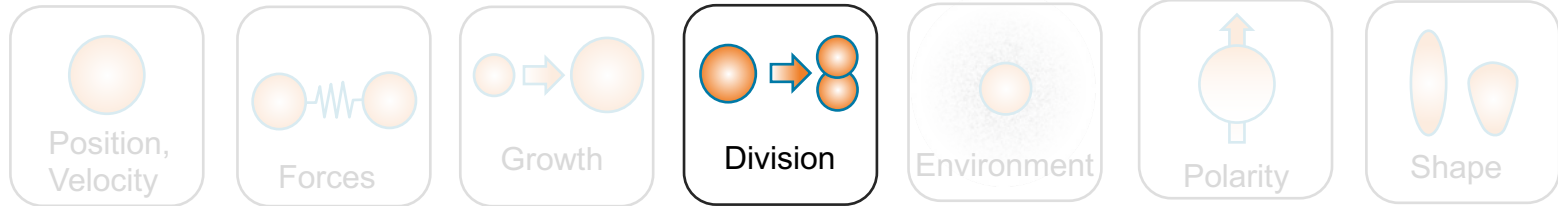
# Agent-based Modeling Toolkit



Pressure-dependent cell growth

$$\frac{dr_i}{dt} = k(\hat{F}_i, |v_i|) \cdot (r_{max} - r_i)$$





## Division (rule-based):

- a second cell centroid is placed in close proximity to the mother centroid
- optional: both cell radii are reduced for volume preservation:  $r_d = \sqrt[3]{1/2} \cdot r_m$
- local mechanics automatically adjusts position of new cells

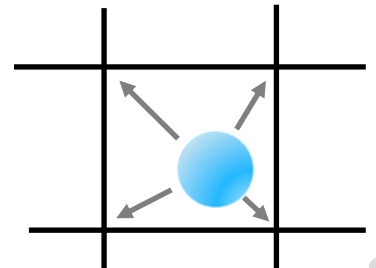
# Agent-based Modeling Toolkit



## Chemical environment:

- Spatio-temporal dynamics of compounds given by systems of partial differential equations
- Sensing and production of chemicals: coupling off-lattice positions to numerical grid
- Active motion term extended by chemotaxis

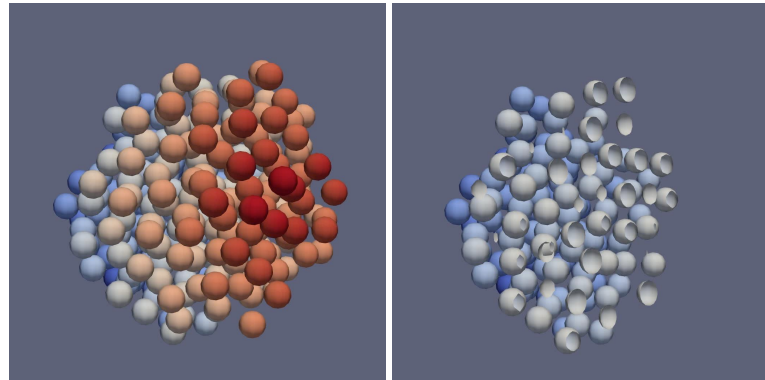
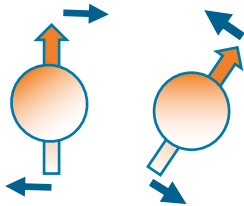
**This results in hybrid discrete-continuous models!**



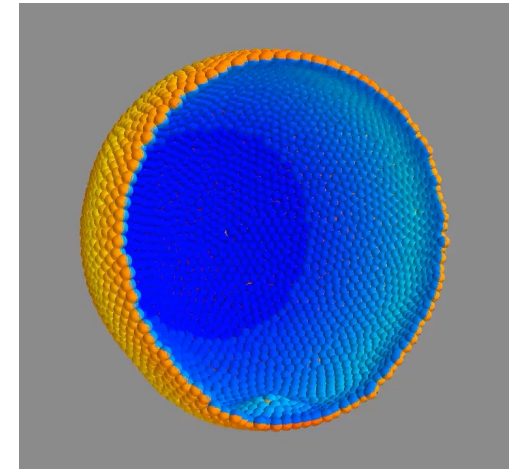
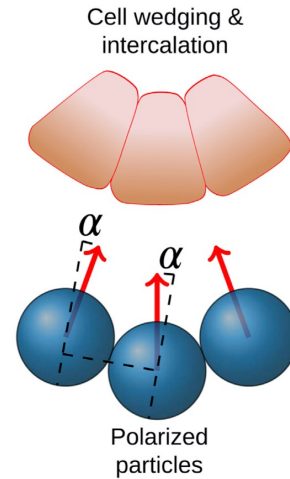
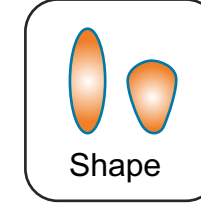
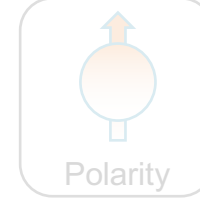
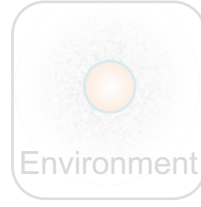
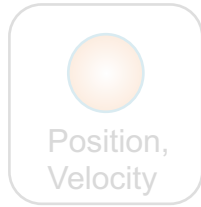
# Agent-based Modeling Toolkit



Spin-dependent force potential



# Agent-Based Modeling Toolkit



## Quantitative Data is Needed for Model Design

How do we 'inform' the models?

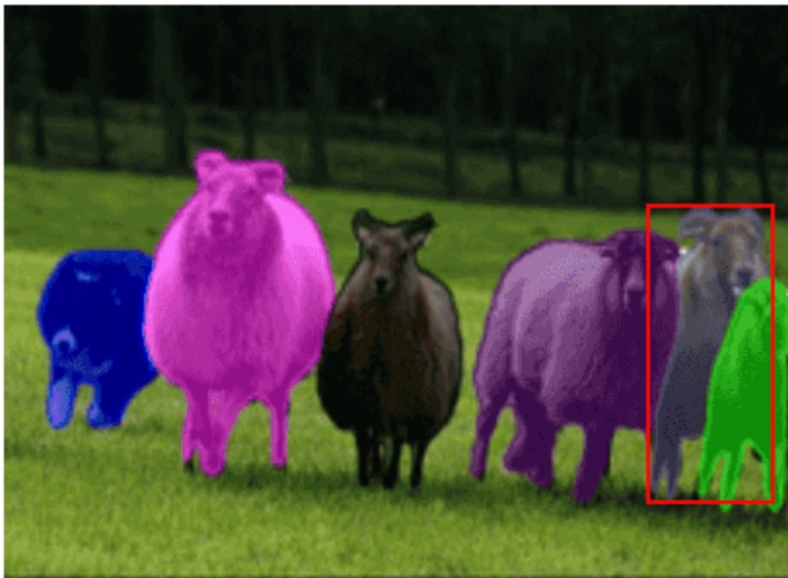
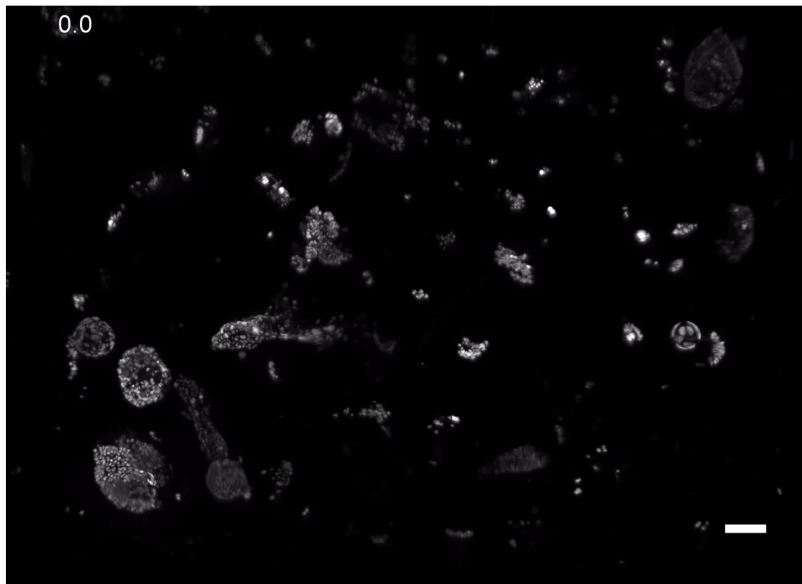


To develop the structure of the model  
(which processes to include) we need  
hypotheses/relations (qualitative data)

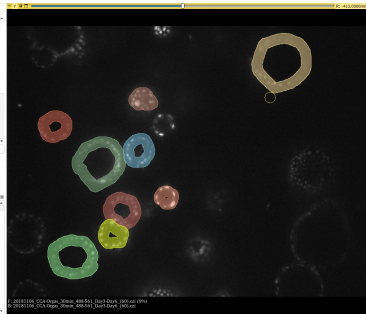


To parametrize the models  
we need quantitative data

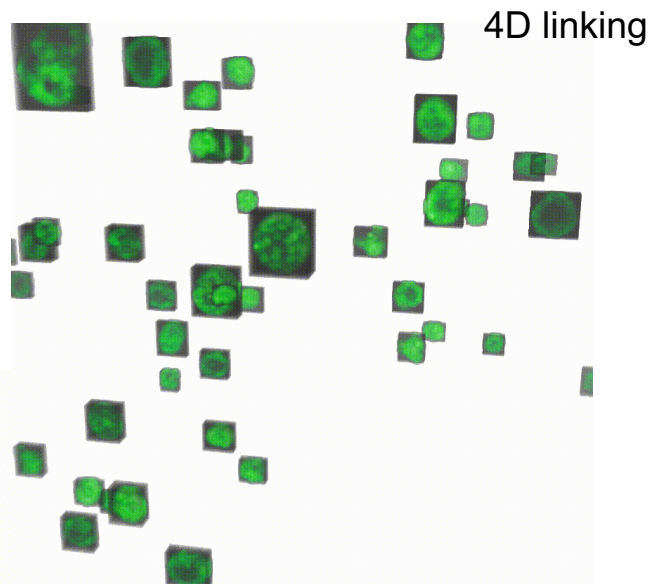
# Instance segmentation (mask\_rcnn) [M. Pereyra]



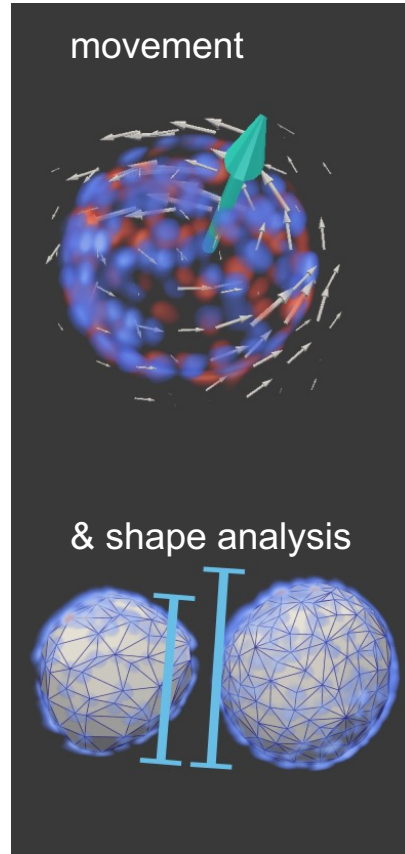
# Object identification



2D Annotation training & prediction

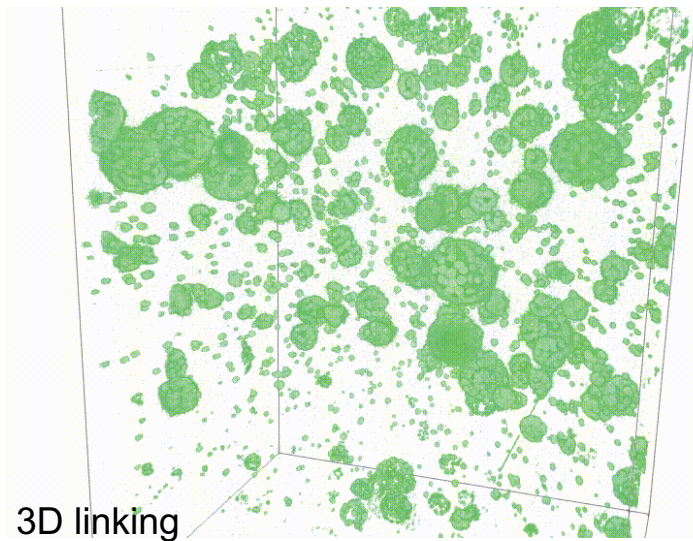


4D linking



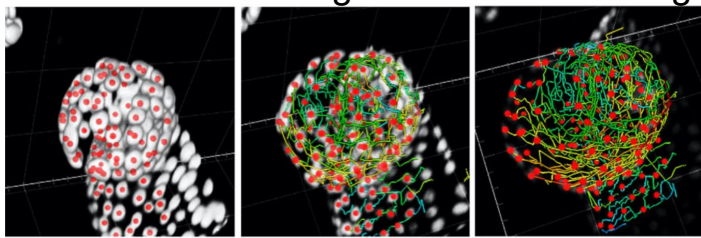
movement

& shape analysis



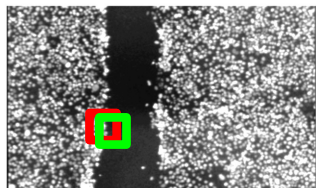
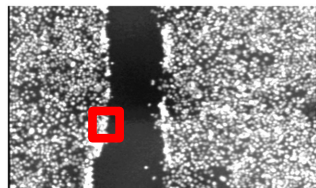
3D linking

Segmentation & tracking



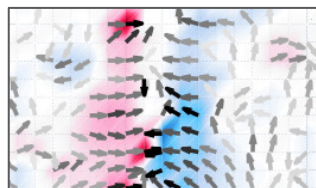


## Particle image velocimetry (PIV)

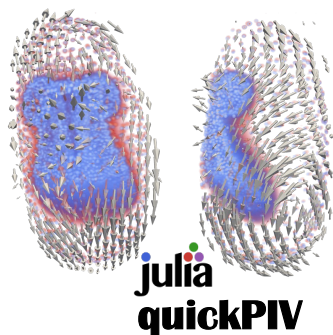


PIV  
→

Velocity field



$$\text{Cross-correlation: } R(\Delta x, \Delta y) = \sum_{k=0}^{K-1} \sum_{l=0}^{L-1} I_1^{i,j}(k, l) \cdot I_2^{i,j}(k + \Delta x, l + \Delta y)$$



Currently **fastest 3D PIV** package available

	C++	OpenPIV (Python)	quickPIV
2D	63 ms	160.81 ms	50.42 ms
3D	--	59.72 s	18.09 s

**Many advantages:**

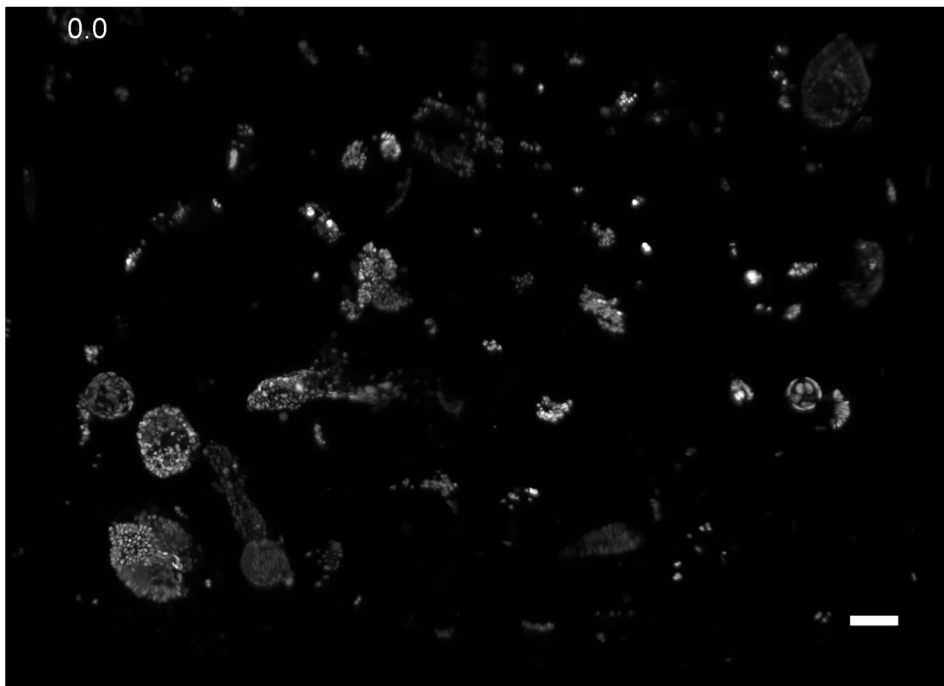
- Fast, robust, reliable
- No problem with cell clusters
- No segmentation needed
- No staining needed

**Features:**

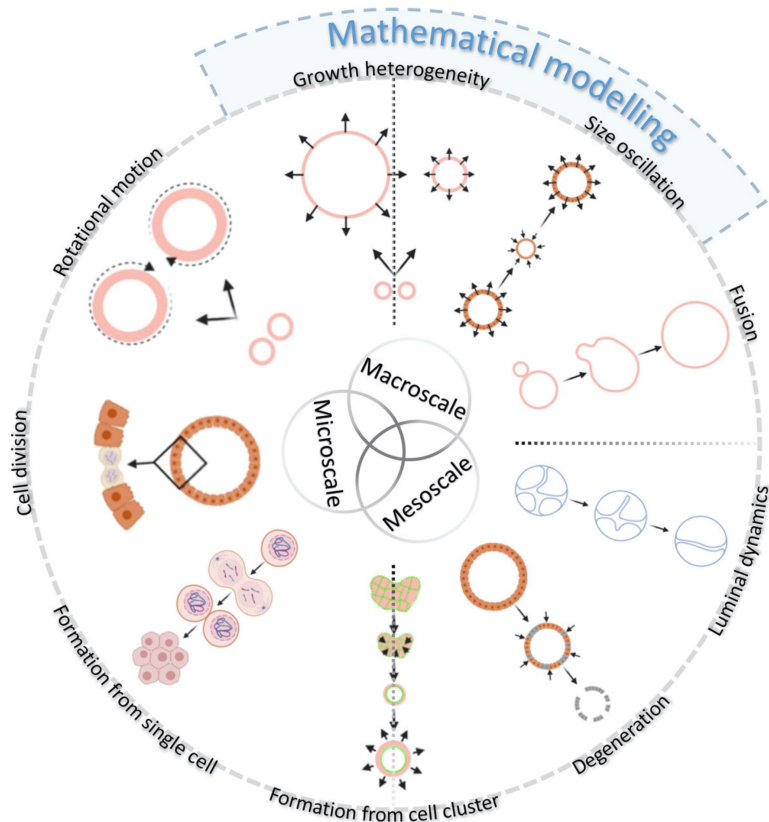
- Cross-correlation
- Peak sub-voxel approximation
- Multi-pass
- Filtering & Post-processing
- Spatial & temporal averaging
- Similarity-selective averaging
- Mappings
- Pseudo-Trajectories

## Example: Dynamics of Pancreas Organoids

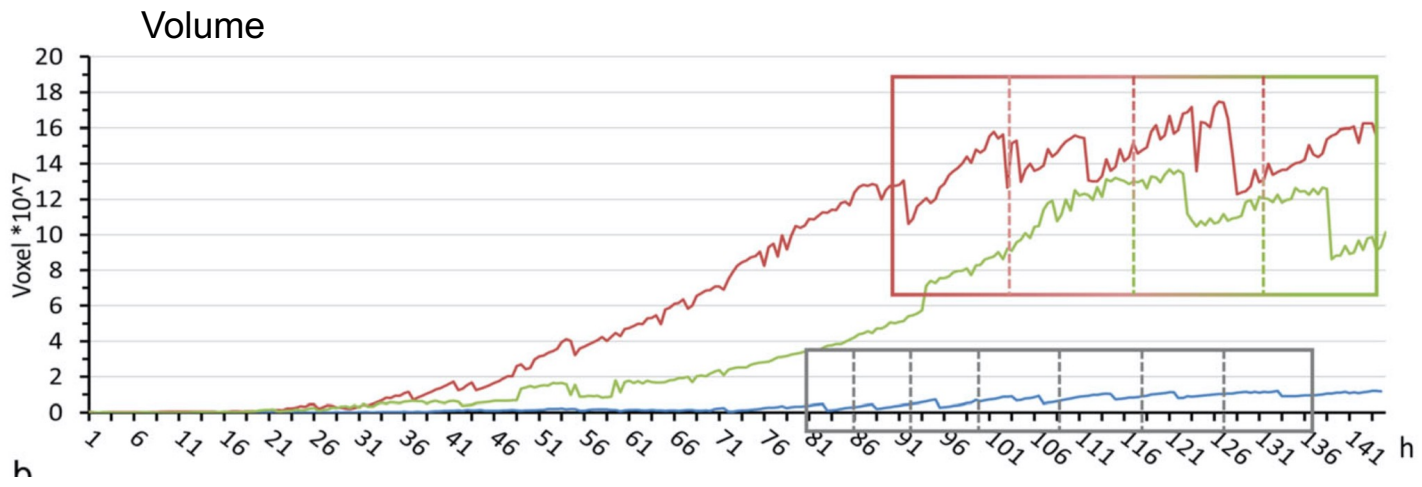
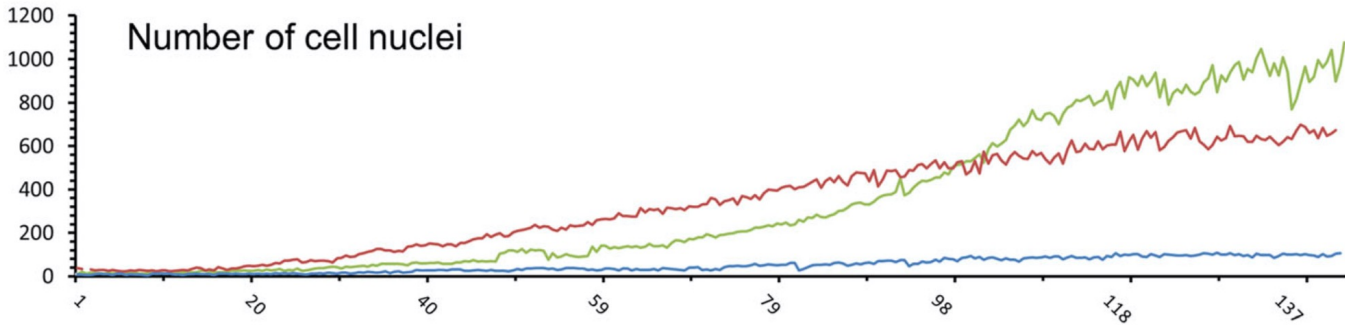
# Pancreas organoid dynamics [T. Liebisch, M. Kurtz]



Pancreas Organoid Dynamics, Stelzer Lab



# Size oscillations [T. Liebisch, M. Kurtz]



## Scaling law for dependence of size oscillation events on cell division dynamics

Volume-area relationship for spherical objects:  $V \sim A^{3/2}$

Production rate of substances is proportional to cell number:  $\dot{n}(t) \sim N(t)$

Osmotic pressure depends on concentration and volume:  $\Pi = c \times i_{vH} \times R \times T = \frac{n}{V} \times i_{vH} \times R \times T \sim \frac{n}{V}$

Surface is proportional to cell count, i.e.,  $N(t) \sim A(t)$ , therefore  $n \sim \int A(t)$

This yields  $\Pi \sim \frac{\int A(t)}{A(t)^{3/2}}$

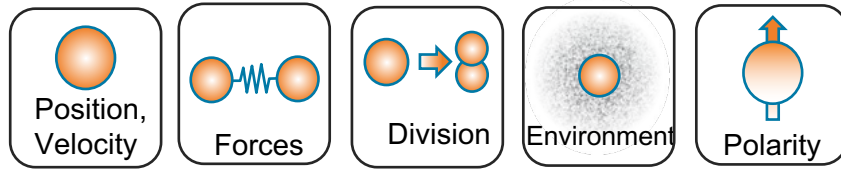
Rupture happens if pressure increases. Constant pressure requires  $\frac{\int A(t)}{A(t)^{3/2}} = \text{const.}$

This is given when  $A(t) \sim t^2$

Constant cell division rate  $\Rightarrow$  exponential increase  $\Rightarrow$  faster than quadratic growth  $\Rightarrow$  expect no ruptures

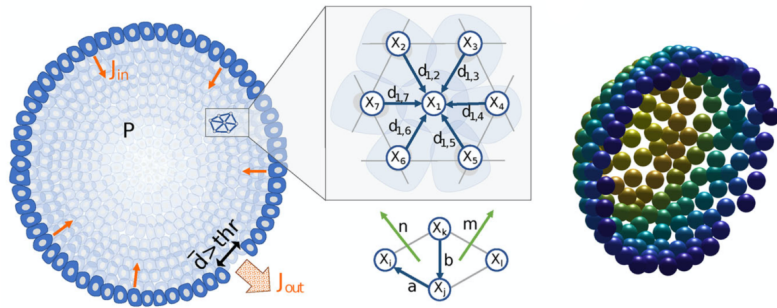
Linear increase in cell number for division rate decreasing as  $1/t$   $\Rightarrow$  expect ruptures

# Agent-based model reproduces organoid dynamics [T. Liebisch, M. Kurtz, L. Ramirez]

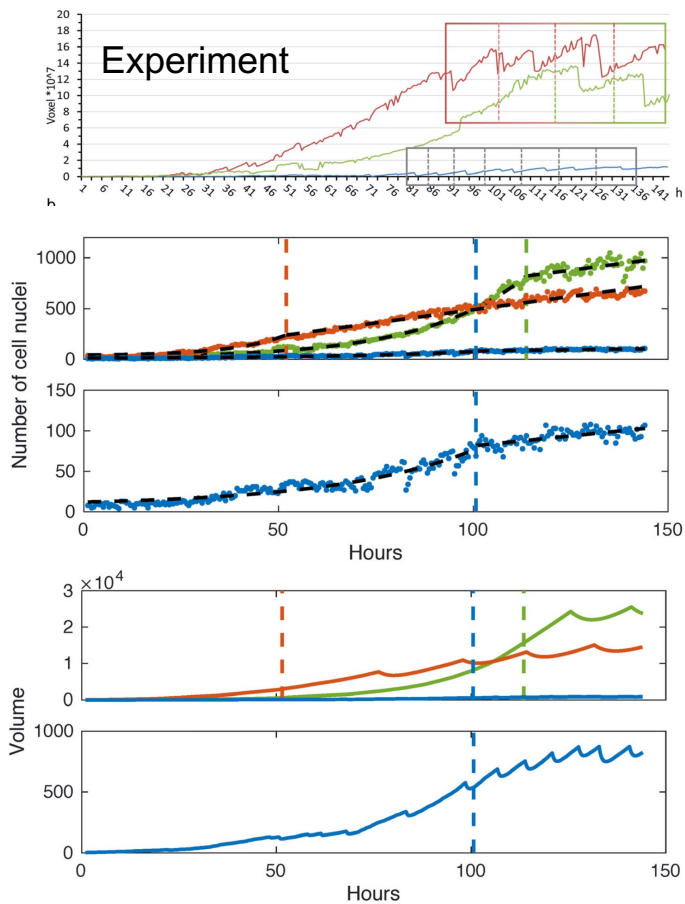


- $F$  includes cell polarity or bending potential
- cell division included
- dynamics of secretion of osmotically active substance
- osmotic pressure  $\Pi = \frac{n}{V} \cdot i_{vH} \cdot R \cdot T$

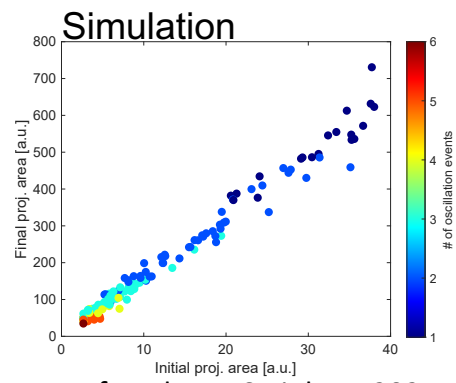
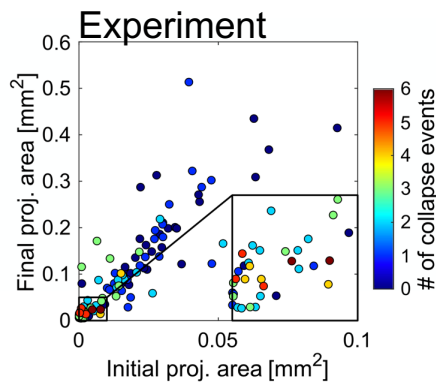
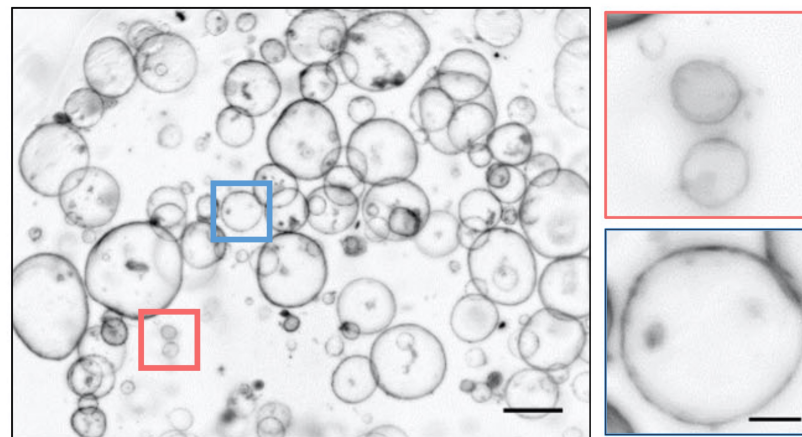
$$\frac{dn}{dt} = NJ_{in} - J_{out}n$$



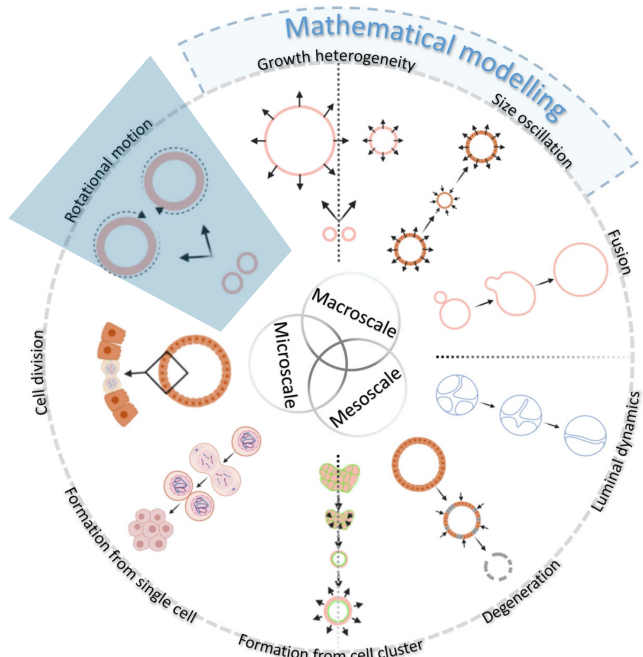
# Agent-based model confirms scaling law



## Further validation using bright-field pipeline

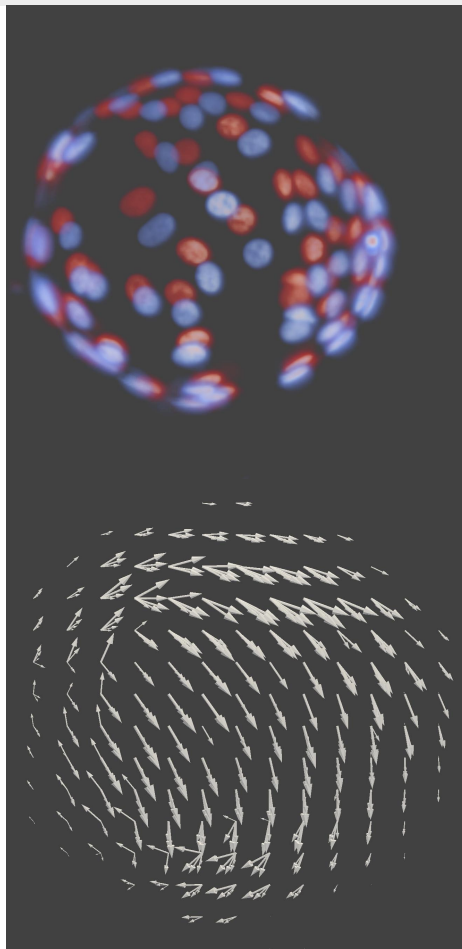


## Further Dynamics: Rotation

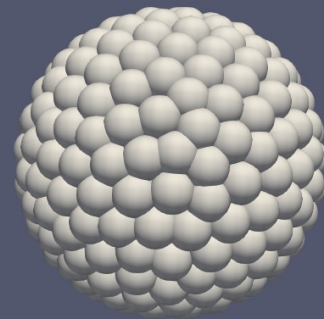


- active migration / acceleration

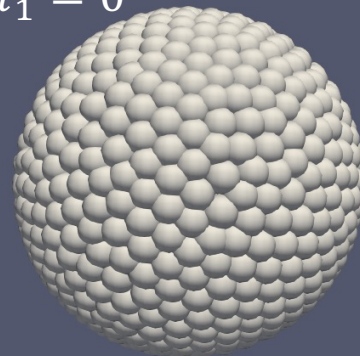
$$\frac{dv}{dt} = \sum A_0 F + \frac{1}{\tau} (v_0 - v)$$



$$\tau_1 = 1$$

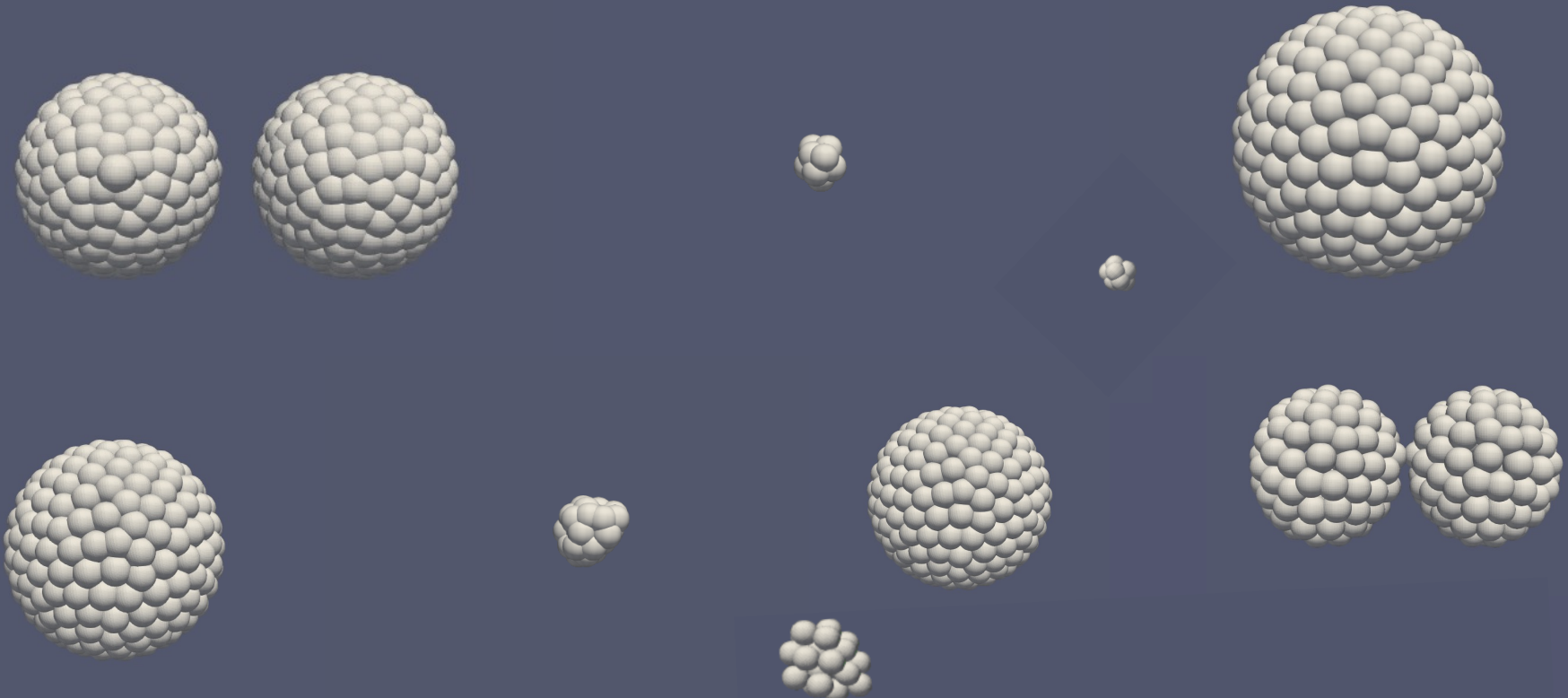
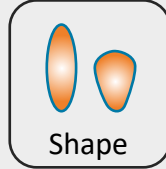
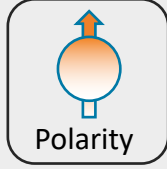
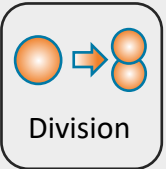
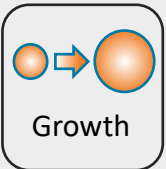
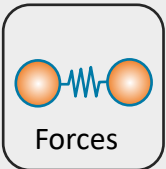
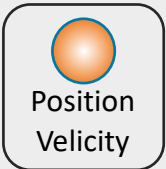


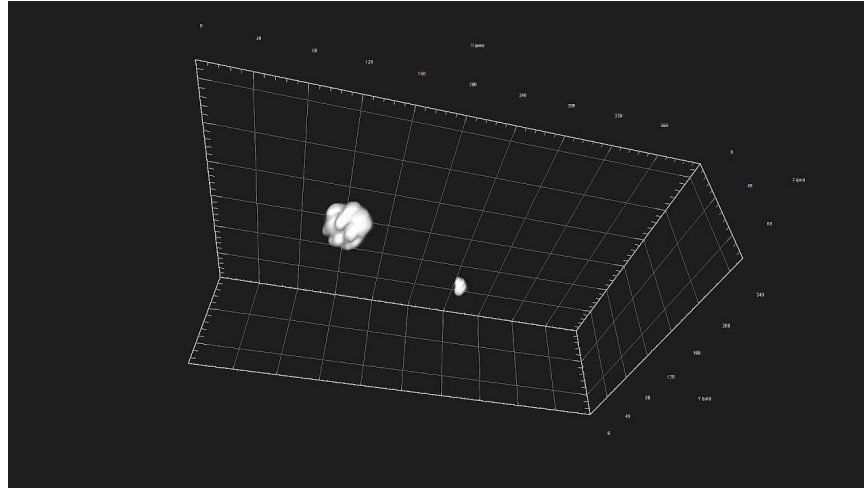
$$\tau_1 = 0$$





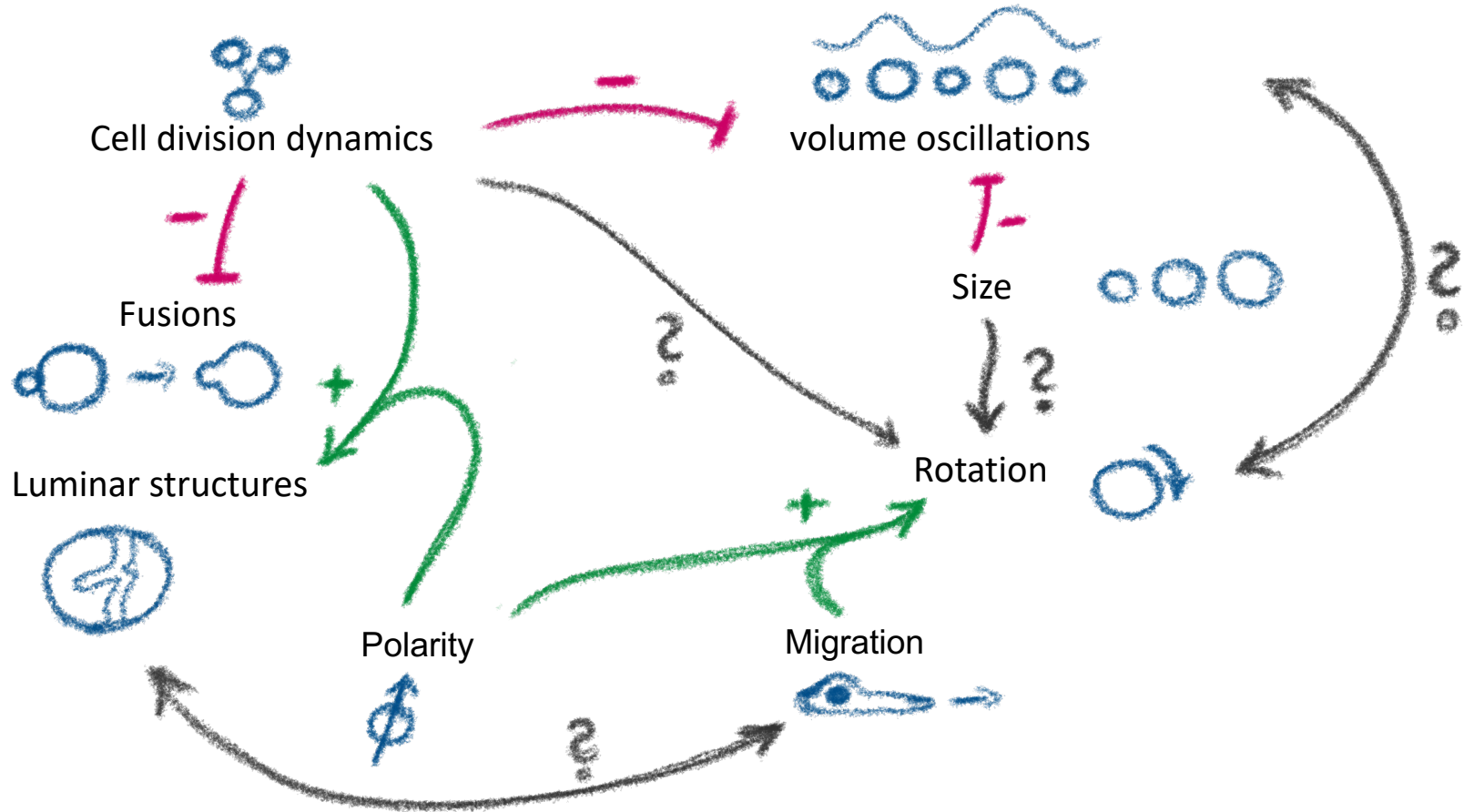
# (Almost) Full Virtual System





Hof et al., BMC Biology, 2021

# What do we learn from these simulations?



## Take Home message:

Agent-based models are useful in determining regulatory processes and biophysical principles underlying collective phenomena in multicellular systems.

## Efficiency / Scaling:

Stochastic simulations are computationally expensive  
Current efforts: increase parallelization / GPU implementation

## Parameter estimation:

Requires summary statistics / large number simulations for every parameter set  
Current efforts: explore AI approaches (simulation-based inference)  
Vision: direct parameter estimation using original data (no summary statistics)

# Acknowledgements

## Cellular Bioinformatics Group

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**LOEWE**

Exzellente Forschung für  
Hessens Zukunft

**CMMS**



**WR**

WISSENSCHAFTSRAT

German Research Council  
High performance computer

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**THANK YOU FOR YOUR ATTENTION**