

UW–Madison Math/CS 714

Methods of Computational Mathematics I

Introduction

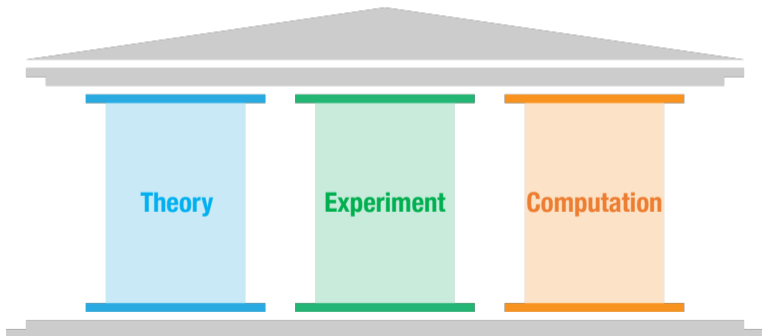
Instructor: Yue Sun (yue.sun@wisc.edu)

September 4, 2025

Three pillars of scientific discovery

theory, experiment, and computation

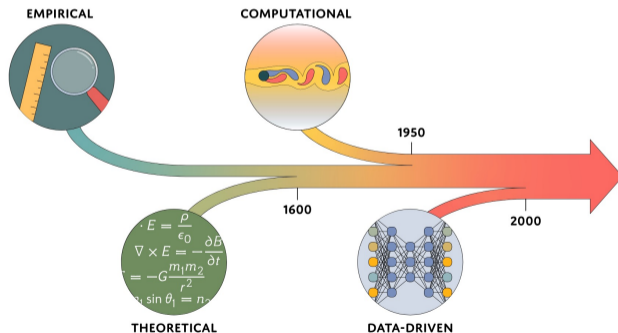
- Computation has been recognized as the “third pillar” of scientific discovery.



Three pillars of scientific discovery

theory, experiment, and computation

- Computation has been recognized as the “third pillar” of scientific discovery.
- *It is also at the core of the emerging **data-driven & machine-learning** scientific paradigm.*



Computational mathematics

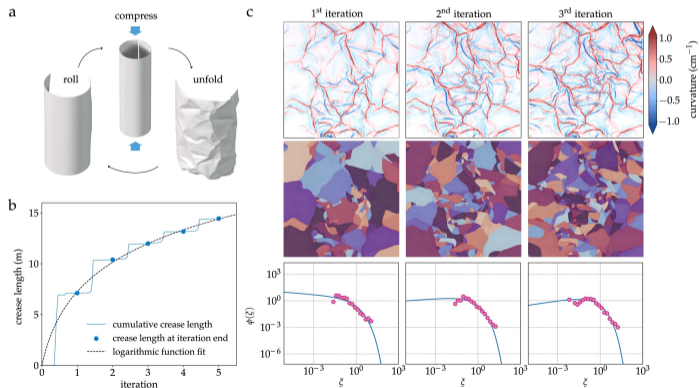
an informal definition

- It is the study of mathematical problems that are solved using **computers**.
- It focuses on developing and analyzing numerical algorithms to obtain **approximate** solutions to problems that may be difficult or impossible to solve analytically, or problems that are highly nonlinear or have multi-physics coupling.
- It has many **real-world** applications, including in physics, engineering, finance, and more.

What can we do with computational mathematics?

simulation of crumpled sheets

- A computational model for simulating the large-scale deformation of thin sheets that can serve as an effective tool for data-driven studies of crumpling dynamics.



What can we do with computational mathematics?

simulation of crumpled sheets

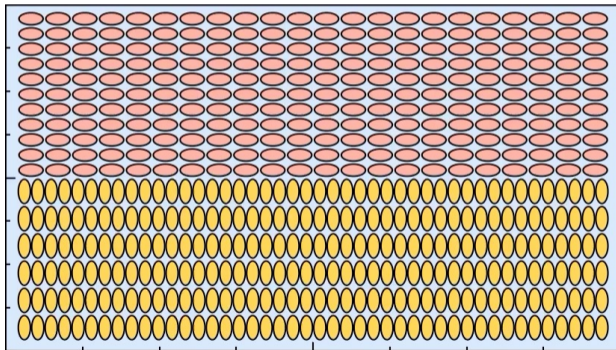


Newton's method, conjugate gradient,
preconditioning, explicit/implicit integration

What can we do with computational mathematics?

simulation of fluid–structure interaction

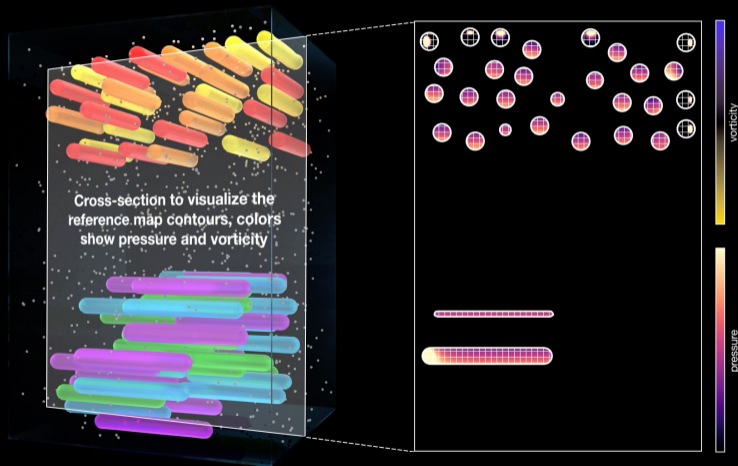
- A computational model for simulating interactions between squishy solids and fluids that can be a tool for studying complex suspension and large-deformation under water.



upwinding finite-difference, methods for fluid simulations

What can we do with computational mathematics?

simulation of fluid–structure interaction

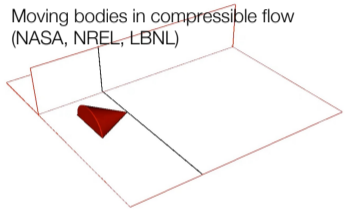


multigrid method, Godunov-type upwinding, projection method

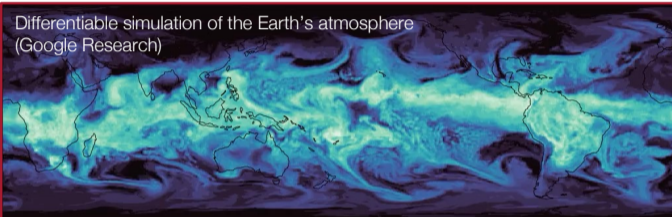
What can we do with computational mathematics?

simulation of more real-world problems

Moving bodies in compressible flow
(NASA, NREL, LBNL)



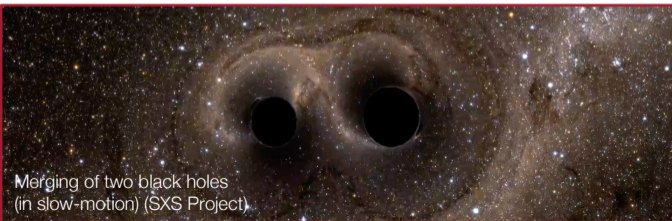
Differentiable simulation of the Earth's atmosphere
(Google Research)



Auto-ignition of a dual-fuel pulse
(NREL, Sandia)



Merging of two black holes
(in slow-motion) (SXS Project)

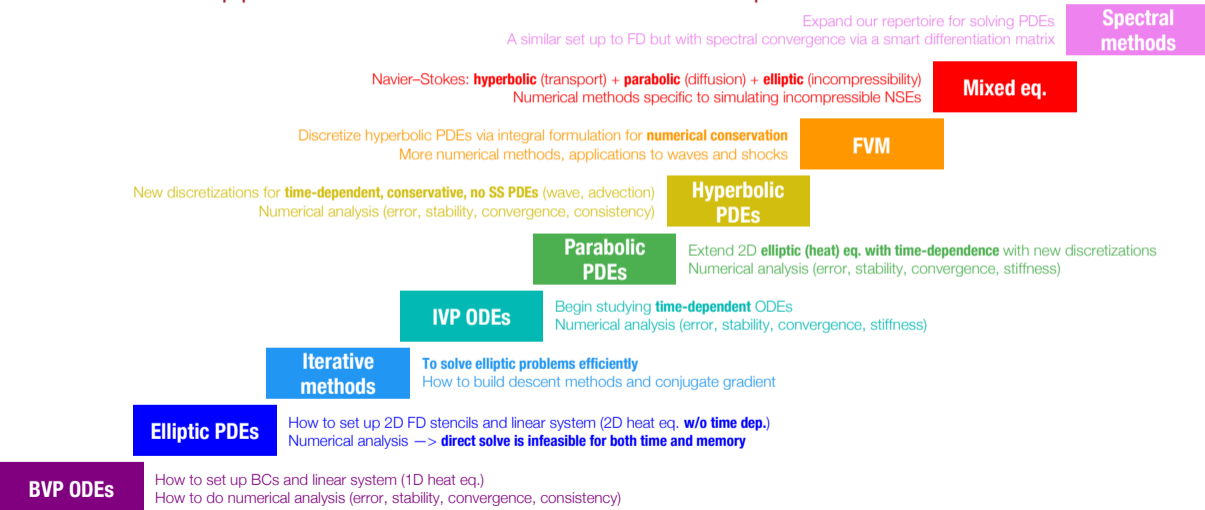


finite volume method

spectral method

Roadmap of the semester

how to approximate solutions to differential equations



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Finite difference approximations

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The finite difference method

There are multiple ways to discretize PDEs, and decompose a continuous problem into a finite, discrete one that can be solved numerically on a computer.

The bulk of this course will focus on the finite difference method, which is effective for a wide range of problems.

There are other approaches (e.g. finite element method, finite volume method, spectral methods). We will explore some of these, although underlying ideas are often similar.

Finite difference approximations

Let $u : \mathbb{R} \rightarrow \mathbb{R}$ be a smooth function, meaning that we can differentiate it several times, and each derivative is a well-defined bounded function over an interval containing a point of interest \bar{x} .

Try approximating $u'(\bar{x})$ by a finite difference approximation using only several values of u near \bar{x} . Obvious choice is

$$D_+ u(\bar{x}) = \frac{u(\bar{x} + h) - u(\bar{x})}{h}$$

where h is a small value.

Called a *one-sided* approximation, since only evaluated at points with $x \geq \bar{x}$.

Matches the definition of the derivative in the limit as $h \rightarrow 0$.

Alternative formula

We could equally use a point in the negative direction, to obtain

$$D_- u(\bar{x}) = \frac{u(\bar{x}) - u(\bar{x} - h)}{h}.$$

An alternative is the *centered approximation*,

$$D_0 u(\bar{x}) = \frac{u(\bar{x} + h) - u(\bar{x} - h)}{2h} = \frac{D_+ u(\bar{x}) + D_- u(\bar{x})}{2}.$$

How accurate are these formulas? How do we derive additional ones?

Truncation errors

The standard approach for error analysis is to perform Taylor series approximations. We have that

$$\begin{aligned}u(\bar{x} + h) &= u(\bar{x}) + hu'(\bar{x}) + \frac{h^2}{2}u''(\bar{x}) + \frac{h^3}{6}u'''(\bar{x}) + O(h^4), \\u(\bar{x} - h) &= u(\bar{x}) - hu'(\bar{x}) + \frac{h^2}{2}u''(\bar{x}) - \frac{h^3}{6}u'''(\bar{x}) + O(h^4).\end{aligned}$$

Then

$$D_+ u(\bar{x}) = \frac{u(\bar{x} + h) - u(\bar{x})}{h} = u'(\bar{x}) + \frac{h}{2}u''(\bar{x}) + \frac{h^2}{6}u'''(\bar{x}) + O(h^3).$$

Leading order term is $O(h)$, so the method is **first order accurate**.

Truncation errors

From Taylor series expansions

$$u(\bar{x} + h) - u(\bar{x} - h) = 2hu'(\bar{x}) + \frac{h^3}{3}u'''(\bar{x}) + O(h^5)$$

since terms with even powers of h cancel. Hence

$$D_0 u(\bar{x}) - u'(\bar{x}) = \frac{h^2}{6}u'''(\bar{x}) + O(h^4).$$

Leading order term is $O(h^2)$, so the method is **second order accurate**.

Deriving finite difference approximations

See [derivation](#): method of undetermined coefficients

Second order derivatives

The same approaches can be used to derive higher order formulae. For example, the standard second order centered approximation is

$$\begin{aligned} D^2 u(\bar{x}) &= \frac{u(\bar{x} - h) - 2u(\bar{x}) + u(\bar{x} + h)}{h^2} \\ &= u''(\bar{x}) + \frac{h^2}{12} u^{(4)}(\bar{x}) + O(h^4). \end{aligned}$$

Due to cancellation of odd powers of h , this formula is second order accurate.

[See derivation](#): a general formula